Application for UNITED STATES LETTERS PATENT

Of

KATSUHIKO TSUNEHARA

and

MIKIO KUWAHARA

EQUIPMENT FOR THE CALCULATION OF MOBILE HANDSET POSITION

EQUIPMENT FOR THE CALCULATION OF MOBILE HANDSET POSITION

5

BACKGROUND OF THE INVENTION

The present invention relates to equipment for locating a current position of a mobile handset by using a radio signal.

JP-A-7-181242 discloses a method for calculating a present position of a mobile handset by using a signal of a cellular telephone. The method of locating the current position of a mobile handset as disclosed in this official gazette will be described 10 below. The mobile handset receives signals transmitted from three cellular telephone base stations. Based on the received signals, the mobile handset calculates differences in propagation time among the signals from the three base stations. The mobile handset, using the propagation time differences, calculates the current 15 position according to triangulation.

SUMMARY OF THE INVENTION

In areas very close to cellular phone base stations or in suburbs or mountainous regions where cellular phone base stations are few, the number of 20 cellular phone base stations that satisfy a reception quality allowing a position measuring operation at the position of the mobile handset decreases. As a result, the number of base stations that satisfy the reception

10

25

quality usable for position calculation becomes fewer than three, making it impossible to use signals from at least three base stations required for position calculation. This renders the locating of the current 5 position of the mobile handset impossible with a conventional method using trilateration. Therefore, in areas where signals from only two or less base stations are available for position calculation, services using the position information cannot be provided.

To solve the problem described above, one aspect of the present invention provides an equipment for calculating the mobile handset position which calculates the number of base stations available for position calculation, performs the position calculation based on trilateration when the number of base stations 15 is three or more, performs the position calculation by using a two-station-based position calculation method when the number of base stations is two, and performs the position calculation by using a one-station-based position calculation method when the number of base 20 stations is one. According to another aspect of the present invention, the equipment controls information to be provided to the mobile handset holder according to the number of base stations available for position calculation.

A more detailed description of the position calculation method will be given later. processing and calculations may be executed by a

processor based on software or by dedicated hardware.

The scope of the present invention includes procedures themselves detailed later with reference to the accompanying drawings, and hardware and software for the procedures.

Other objects, features and advantages of the invention will become apparent from the following description of the embodiments of the invention taken in conjunction with the accompanying drawings.

10 BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a block diagram showing a configuration of equipment implementing the present invention.

Fig. 2 is an operation flow of a position 15 calculation unit 400.

Fig. 3 illustrates a first example configuration realizing a position calculation step for two base stations 421.

Fig. 4 illustrates a second example

20 configuration realizing the position calculation step
for two base stations 421.

Fig. 5 illustrates a third example configuration realizing the position calculation step for two base stations 421.

Fig. 6 illustrates a first example embodiment realizing a position calculation step for a single base station 431.

Fig. 7 illustrates a second example configuration realizing the position calculation step for a single base station 431.

Fig. 8 illustrates an operation of a position information application unit 500.

DETAILED DESCRIPTION OF THE EMBODIMENTS

A configuration of the equipment implementing the present invention is shown in Fig. 1. A signal receiver 101 performs reception processing at a

10 high/intermediate frequency corresponding to a cellular signal received by an antenna 100 and also demodulation processing on a base band signal to generate a cellular reception signal 102.

A position calculation information generator 15 103 generates, from the cellular reception signal 102, position calculation information 104 necessary for position calculation and outputs it to a base station selection unit 105. The information required for position calculation includes, for example, a reception 20 timing of the cellular signal from base stations and a reception quality of the cellular signal from base stations. The reception timing may be determined, for example, by using a matched filter and producing a delay profile of the received signal. The reception 25 quality of the cellular signal may be determined from a correlation value of the delay profile.

According to the position calculation

information 104 received, the base station selection unit 105 selects base stations available for the position calculation and outputs position calculation information 106 on the selected base stations to a base 5 station number counter 200 and the position calculation unit 400. For example, the method of selecting the base stations may select only those base stations whose signal-to-noise ratios of the received signals are in excess of a predetermined threshold.

10 The base station number counter 200 counts the number of base stations selected by the base station selection unit 105 and outputs the selected number of base stations 201 to a position calculation method controller 300.

The position calculation method controller 300 outputs to the position calculation unit 400 and a position information application unit 500 a control signal 301 that controls, according to the selected number of base stations 201, the position calculation 20 method to be performed by the position calculation unit 400. In this embodiment, when the selected number of base stations 201 is one, the control signal 301 is set to 1; when the base station number is two, the control signal 301 is set to 2; and when the number is three or 25 more, the control signal 301 is set to 3.

The position calculation unit 400 selects the position calculation method according to the control signal 301, calculates the current position of a mobile

COCLED + BEELDE

1.5

25

440).

handset by using the position calculation information 106 on the base stations selected by the base station selection unit 105, and outputs a position calculation result 401. The operation flow of the position 5 calculation unit 400 will be explained by referring to Fig. 2. The position calculation unit 400 checks if the control signal 301 is "3" or not (step 410). the control signal 301 is "3", the position calculation unit 400 performs the position calculation based on 10 trilateration (step 411). When the control signal 301 is not "3", the position calculation unit 400 checks whether the control signal 301 is "2" (step 420). If the control signal 301 is "2", the position calculation unit 400 performs the position calculation according to 15 a 2-station-based position calculation method (step 421). When the step 420 finds that the control signal 301 is not "2", i.e., the control signal 301 is "1", the position calculation unit 400 performs the position calculation according to a 1-station-based position calculation method (step 431). The position calculation unit 400 outputs a position calculation result 412, 422, 432 as the position calculation result 401 produced by the position calculation method selected according to the control signal 301 (step

Fig. 3 shows a first example configuration of the 2-station-based position calculation step 421. In this example, of the position calculation information 106 on the base stations selected by the base station selection unit 105, first and second base station positions (X_1, Y_1) and (X_2, Y_2) are used for position calculation. A base station positions averaging unit 600 calculates X and Y component averages of (X_1, Y_1) and (X_2, Y_2) and outputs them as a mobile handset position (X, Y).

Fig. 4 shows a second example configuration of the 2-station-based position calculation step 421.

- In this example, of the position calculation information 106 on the base stations selected by the base station selection unit 105, first and second base station positions (X_1, Y_1) and (X_2, Y_2) and reception qualities of signals received from the first and second
- base stations, W_1 , W_2 , are used for position calculation. In this embodiment, a signal-to-noise ratio SNR is used as the reception quality of the received signal. As another reception quality a reception power of the received signal may be used.
- The base station positions averaging unit 600 calculates weighted averages from the X and Y components of (X_1, Y_1) and (X_2, Y_2) with the reception qualities W_1 and W_2 taken as weights and outputs a mobile handset position (X, Y).
- Fig. 5 shows a third example configuration of the 2-station-based position calculation step 421. The position calculation information 106 on the base stations selected by the base station selection unit

105 is input to a trilateration operation unit 602 and a base station information storage 603. The base station information storage 603 holds position calculation information used in the past position 5 calculations. In this example, the base stations selected by the base station selection unit 105 are two stations, a first base station and a second base station, which is one station short of the requirement for trilateration. Hence, the base station information storage 603 selects position calculation information 604 on a third base station, different from the first and second base stations, from among the position calculation information used in the past position calculations, and outputs the selected information to 15 the trilateration operation unit 602. The method for selecting the third base station, for example, needs only to select a base station different from the first and second base stations from among the base stations used in the latest position calculation. When there 20 are two or more such base stations, one with the best reception quality may be chosen. The trilateration operation unit uses the position calculation information on the first and second base stations entered from the base station selection unit 105 and the position calculation information on the third base station entered from the base station information storage 603 to perform the position calculation based on the principle of trilateration and then outputs a

- 9 -

mobile handset position 422.

Fig. 6 shows a first example configuration of the 1-station-based position calculation step 431. In this example, of the position calculation information 106 on the first base station selected by the base station selection unit 105, the first base station position (X_1, Y_1) is used for the position calculation. A base station position output unit 700 outputs the position (X_1, Y_1) as the mobile handset position (X, Y).

10 Fig. 7 shows a second example configuration of the 1-station-based position calculation step 431. The position calculation information 106 on the base station selected by the base station selection unit 105 is entered into a trilateration operation unit 701 and 15 a base station information storage 702. The base station information storage 702 holds position calculation information used in the past position calculations. In this embodiment, the base station selected by the base station selection unit 105 is only 20 one station, a first base station, which is two stations short of the requirement for trilateration. Hence, the base station information storage 702 selects position calculation information 703 on the second and third base stations, different from the first base 25 station, from among the position calculation information used in the past position calculations and

then outputs the selected information to the

trilateration operation unit 701. The method for

selecting the second and third base stations, for example, needs only to select two base stations different from the first base station from among the base stations used in the latest position calculation.

- When there are two or more such base stations, two with the best reception qualities may be chosen. The trilateration operation unit uses the position calculation information on the first base station entered from the base station selection unit 105 and the position calculation information on the second and third base stations entered from the base station information storage 702 to perform the position calculation based on the principle of trilateration and then outputs a mobile handset position 432.
- 15 The position information application unit 500 uses the received position calculation result 401 and control signal 301 to provide a mobile handset holder with services using position information, such as offering nearby store information and route guidance.
- 20 Fig. 8 shows an operation of the position information application unit 500 when it provides the nearby store information as the service using position information. It is assumed that the position calculation result 401 represents a position 800 as a current position. First, a case where the control signal 301 is "3" will be explained. In this case, the number of base stations used in the position calculation is three or more and the accuracy of the

position calculation result 401 is considered good. The position information application unit 500 provides the mobile handset holder with information on stores 810 and 811 in an area 801 as the nearby store

- information. Next, a case in which the control signal 301 is "2" will be explained. In this case, the number of base stations used in the position calculation is two and the accuracy of the position calculation result 401 is considered worse than that when the control
- signal 301 is "3". In this case, the position information application unit 500 provides the mobile handset holder with information on stores 810, 811 and 812 in an area 802 wider than the area 801 as the nearby store information. Finally, a case where the
- case the number of base stations used in the position calculation is one and the accuracy of the position calculation result 401 is considered still worse than when the control signal 301 is "2". The position
- information application unit 500 provides the mobile handset holder with information on stores 810, 811, 812 and 813 in an area 803 wider than the area 802 as the nearby store information.

As described above, even when the position

25 locating accuracy is poor, the position information application unit 500 can provide the mobile handset holder with the nearby store information by controlling the area for the store information being provided

according to the position locating accuracy.

With this invention, even in areas where signals from only two or less base stations are available for the position calculation, the current 5 position of the mobile handset can be determined. makes it possible to expand the area of the position information service. Further, by controlling the information to be provided to the user according to the number of base stations used in the position 10 calculation, it is possible to offer useful information to the user even when only one base station is available for the position calculation and the position locating accuracy is bad. The usefulness of the position information service can therefore be enhanced.

15 It should be further understood by those skilled in the art that the foregoing description has been made on embodiments of the invention and that various changes and modifications may be made in the invention without departing from the spirit of the invention and the scope of the appended claims.